

#### Implantable chronic Brain Machine Interface for movement compensation: from clinical proof of concept to daily use

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# WIMAGINE-BCI : a CEA technology



#### WIMAGINE® IMPLANT

- Chronic ECoG recording on 64 channels
- Wireless transmission
- Remote power supply
- AIMD class III regulatory compliance for long-term clinical applications

Mestais et al. 2014 *IEEE transactions on neural systems and rehabilitation engineering.* 



#### BRAIN SIGNAL DECODER

Artificial Intelligence methods

- High dimensional decoding (multi-limb)
- Real time adaptive learning of models (recursive model)
- Stability and Robustness over time

Eliseyev A. et al. PLOS ONE, 2016 Benabid, A. L. et al. The Lancet Neurology 2019 Eliseyev, A., et al. 2017. Scientific reports Moly, A., et al. 2022 J. Neural Eng.

A portfolio of 25 patents on the WIMAGINE-BCI technology

CES

2024

# **BCI WIMAGINE DEVELOPMENT AND CLINICAL VALIDATION : A LONG JOURNEY**





# linatec Clinical trial "BCI & Tetraplegia" 1<sup>st</sup> clinical evaluation of the WIMAGINE-BCI technology



## Goal

Providing the proof of concept that it is possible, for tetraplegic patients to control complex effectors, such as a 4-limb exoskeleton, thanks to brain activity monitoring and decoding

Under the scientific direction of **Professor Alim-Louis BENABID** (Lasker~DeBakey Prize 2014 & Breakthrough Prize 2015)

Principal Investigator: **Professor Stéphan Chabardès** 







#### **Clinical trial "BCI & Tetraplegia"** Proof of concept of a high dimensional control of complex effector using ECoG brain signal







Walking control

3D continuous trajectories and pronation/supination control of 2 arms 8D multi-limbs control



THE LANCET Neurology Benabid, A. L., Costecalde, T., Eliseyev, A., Charvet, G., Verney, A., Karakas, S., ... & Chabardes, S. (2019). An exoskeleton controlled by an epidural wireless brain–machine interface in a tetraplegic patient: a proof-of-concept demonstration. *The Lancet Neurology*, *18*(12), 1112-1122.

# clinated Brain signal decoder based on machine learning techniques





#### RECURSIVE EXPONENTIALLY WEIGHTED MARKOV-SWITCHING MULTI-LINEAR MODEL (REW-MSLM)





# **Real-time Incremental training**



# clinatec A progressive training (real / virtual effectors)

Walking control training sessions

#### Mental tasks:



- **Brain switch** to activate an automatic walking cycle
- **Training with virtual** environment and exoskeleton











Walking training session

**Upper limb control** training session



- Continuous trajectories decoding: wrist translation
- Training with virtual environment • and exoskeleton











Left arm control training session



- Continuous trajectories decoding: alternative wrists translation + rotation
- Training with virtual environment ٠ and exoskeleton

3D avatar





Multi-Limb training session



### **Demonstration of a long-term stable and robust bimanual control**

Demonstration of the stability of performances with an 8D decoding model over a period of 6 months without recalibration :

- 8D exoskeleton experiment (167 days)
- 8D virtual avatar experiment (203 days)

Perspectives of chronic use of the WIMAGINE technology



Moly et al. 2022, An adaptive closed-loop ECoG decoder for long-term and stable bimanual control of an exoskeleton by a tetraplegic. 2022 *J. Neural Eng.* 

# **BCI and sensor-based shared control to assist and secure user for mobility and reach-and-grasp tasks**



#### **Grasping assistance (robotic arm control)**



#### Mobility assistance (wheelchair driving)





Bellicha, A., Struber, L., Pasteau, F., Juillard, V., Devigne, L., Karakas, S., ... & Charvet, G. (2025). Depth-sensor-based shared control assistance for mobility and object manipulation: toward long-term home-use of BCI-controlled assistive robotic devices. *Journal of Neural Engineering*.

# **Evaluation of BCI and sensor-based** shared-control technology

#### Grasping tasks (robotic arm control with and without shared control)



#### Mobility tasks (wheelchair driving with and without shared control)





Shared control benefits:

- Time to perform the task :
- Cognitive load (estimated) :
  - All collisions avoided in wheelchair driving
- No « unwanted » grasps in robotic arm control

Shared control

Yes

No

Bellicha, A., Struber, L., Pasteau, F., Juillard, V., Devigne, L., Karakas, S., ... & Charvet, G. (2025). Depth-sensor-based shared control assistance for mobility and object manipulation: toward longterm home-use of BCI-controlled assistive robotic devices. *Journal* of Neural Engineering.



#### GAIT RESTORATION FOR PARAPLEGIC PATIENT WITH A BRAIN SPINE INTERFACE





Cortical implants





WIMAGINE-BCI technology







nature

Walking natur using a brain-s	ally afte pine int	r spinal cord injury cerface
https://doi.org/10.0336/s41586-023-06098-5 Received: 17.6gost:2022 Accepted: 17.8gost:2023 Published ontine: 24 May 2023	Here targets <sup>(11)</sup> , Rocket inform <sup>(12)</sup> , "Attach targets <sup>(12)</sup> , "Into Honor, Target Andrew, Targets The second se	
Open access		
To well, the brain delivers executive commands to the ensures located in the lamboscoti spitel corel. Although the majority of spital core lighteness do not deredly darage three meaners, the discreption of doccarding pathways interrupts the train-derived commands that encoccurs for the ensemances on portice welling. <sup>16</sup> Concemponent is premised blowed that epidaral electrical stimulation target-		Here, we suggest that a digital bridge "= "between the brain and spinal cord would enable voltional control over the timing and amplitude of musel a catchy, researing more nearcal and adaptive control of Landing and walking in people with purelysis due to optical conflictions.
ing the individual dorsal root entry zones of the lambes acral spinal conductive the model at how the second statistics of specific law and the law to the second statistics of specific law and the s		Digital bridge from brain to spinal cord Taostablish this distral bridge, we interneted two fields involuted set-
Core consists for incontances spectra spectra provide point. In this, recruiting these constrainest errors, where with prepringenament liquid nonropeous sequences replication the physiological activation of large mesor pools and/white gravitational and walking trained. These stimula- tion sequences restand standing and basic walking in people with paralysis data in a spikal core legiting. However, this recovery required warable methics some to deter theorie metaching for horiz reducta-		term that enable recording of cortical activity and stienalation of the
		hummous rangement even were and a mean weat time in pipe tail. To monitor decrements carging pipes (ECGO) signals from the sensor- ments cortex, we leverage of the WMAGNE technology <sup>1,10</sup> . WMAGNE implement consist of an 8-by 8 grid of 64 electronics (4 mm + 4.5 mm) pitch in anterepote trive and needloakers alson, respectively) and
movements or compensatory strategies to initiate the proprogrammed utimulation sequences? Consequently, the control of walking second		recording electronics that are embedded within a 50 mm diameter, circular shaped ittaniam, are that has the same thickness as the shall.
perceived as completely natural. Moreover, the participants showed		The geometry of the system favorars close and stable contact between

Lorach, H., Galvez, A., Spagnolo, V., Martel, F., Karakas, S., Intering, N., ... G. Charvet, J. Bloch & Courtine, G. (2023). Walking naturally after spinal cord injury using a brain–spine interface. *Nature*, *618*(7963), 126-133.



Grégoire Courtine

Jocelyne Bloch Henri Lorach

<u>cea</u>

### **BILATERAL IMPLANTATION OVER SENSORIMOTOR CORTEX**

#### **CONVERTING THOUGHTS INTO ACTIONS**









# Next steps: towards fully autonomous home-use BCI system



PORTABLE, EASY TO USE AND ESTHETIC SYSTEM FOR EVERYDAY USE AND ENHANCED ACCEPTABILITY



BCI DECODING INTEGRATED CIRCUIT FOR MINIATURIZATION



ADAPTIVE DECODER FOR LONG TERM USE



BRAIN-GUIDED SPINAL CORD STIMULATION FOR BEST MOTOR PERFORMANCES



# linated Towards the evaluation of new clinical applications



#### **NEUROREHABILIATION FOR POST-STROKE PATIENT**



Upper limb and lower limb restoration in chronic stroke patients with BCI combined to rehabilitation effectors



horizon

**REVERSE STROKE** 









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